

VMC: Recent Advances and Challenges Ahead

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Disclaimer and acknowledgement

- My talk is about the variability model checker VMC, hence. . .
- normally I would now start by explaining what VMC is all about, but I assume that you stayed awake during Stefania's keynote 😊
- VMC is a product of the KandISTI family of model checkers that has been developed at ISTI-CNR over the last two decades
- Its main developer is Franco Mazzanti, but many other members of ISTI's Formal Methods && Tools lab have contributed to its development, in particular Stefania Gnesi & Alessandro Fantechi
- This family of model checkers has been developed during a series of EU projects (Agile, Sensoria, Quanticol, LearnPAd)

Outline

- 1 KandISTI: A family of model checkers
- 2 Variability Model Checker (VMC)
 - Modal Transition Systems with variability constraints
 - variability-aware ACTL: A logic to express variability
- 3 VMC: Recent advances
 - Full integration in KandISTI
 - A value-passing modal process algebra
 - n -ary variability constraints
 - Preservation of verification results
- 4 An example family of Bike-Sharing Systems (BSS)
- 5 Conclusions and challenges ahead

A family of model checkers

KandISTI 2014

CMC

FMC

VMC



UMC



<http://fmt.isti.cnr.it/kandisti/>

Main features

- Four different specification languages, one **common verification engine**
- Manually explore a system's evolutions and generate a summary of its **behavior** — powerful minimization techniques
- Investigate abstract system properties by using a branching-time temporal logic supported by an **on-the-fly** model checker
- The fragment of this logic without fixed-point operators allows verifications with a complexity which is **linear** with respect to the size of the model and the size of the formula
- Obtain a clear **explanation** of the model-checking results in terms of possible evolutions of the specific computational model
- Current limit for an exhaustive verification is a statespace of **millions of states**

FMC: origin of our on-the-fly model-checking approach

- A system is a hierarchical composition (net) of sequential **automata** (terms)
- Terms can be recursively defined using a simple **process algebra** which supports features coming from CCS, CSP and LOTOS
- Communication and synchronization among terms is achieved through synchronous operations over channels
- Term definitions can be parametrized, and communication operations allow (integer) **value passing**
- **Bounded** model-checking (also useful for explanations)
- **Action-based** branching-time logic inspired by ACTL and enriched with weak until operators, box/diamond operators and fixed-point operators

UMC: Support for state/event-based models and logics

ter Beek, Fantechi, Gnesi, Mazzanti @ *Sci. Comput. Program.*, 2011

- A system is a set of communicating UML-like **state machines**
- $\langle Source \rangle \rightarrow \langle Target \rangle \{ \langle EventTrigger \rangle [\langle Guard \rangle] / \langle Actions \rangle \}$
- UCTL: an **action- and state-based** logic
- Allows to express not only properties of evolution steps (i.e. related to the executed actions) but also internal properties of states (e.g. related to the values of object attributes)
- Actual system structure defined by a set of active object instantiations
- A full UMC model is defined by a sequence of Class and Objects declarations and by a final definition of a set of Abstraction rules
- The overall behavior of a system is formalized as an abstract **L²TS** and **abstraction** rules allow to define what we want to see as labels of the states and edges of the L²TS

CMC: Parametrized logic formulas for expressing data correlations among actions

Fantechi, Gnesi, Lapadula, Mazzanti, Pugliese, Tiezzi © ACM TOSEM, 2012

- A system is specified in COWS: Calculus for Orchestration of Web Services
- Allows to model service publication and discovery, SLA negotiation, orchestration, service interactions and compositions, fault and compensation handling
- SocL: a logic allowing to express the **correlation** between dynamically generated values appearing inside actions at different times, representing the correlation values which allow, e.g., to relate the responses of a service to their specific request, or to handle the concept of a session involving a long sequence of interactions among the interacting partners
- $AG [request(p, \$id)] AF response(p, \%id) true$

VMC: Behavioral variability analysis for product families

ter Beek, Mazzanti, Sulova @ FM'12; ter Beek, Gnesi, Mazzanti @ SPLC'12

- A system is specified as a **Modal Transition System** in process-algebraic terms, together with an optional set of **variability constraints**
- VMC allows two kinds of behavioral variability analyses
 1. A logic property expressed in a variability-aware version of ACTL (v-ACTL) can directly be verified against the MTS modeling the **family behavior**, relying on the fact that under certain syntactic conditions the validity of the property over the MTS guarantees the validity of the same property for all products of the family
 2. The actual set of valid **product behavior** can explicitly be generated and the resulting LTSs can be verified against the same logic property (expressed in ACTL), which is surely less efficient than direct MTS verification but allows to precisely identify the set of features whose interactions may cause the original property to fail over the whole family

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VMC (cont'd)

- The abstract model associated to this variability-oriented process algebra is an L^2TS in which edges are labelled with sets of labels, and where the additional 'may' label is added to the optional edges to specify variability — could easily add **features** as well
- v-ACTL is built over a subset of ACTL, but enriched with **deontic** operators AF^\square , EF^\square and $\langle \rangle^\square$, which are actually implemented in VMC by a **translation** into plain ACTL



$$T = a.T + b(\text{may}).\text{nil}$$

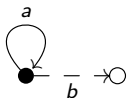
$$\langle a \rangle^\square \text{ true}$$



$$\langle a \wedge \neg \text{may} \rangle \text{ true}$$

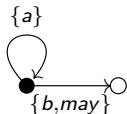
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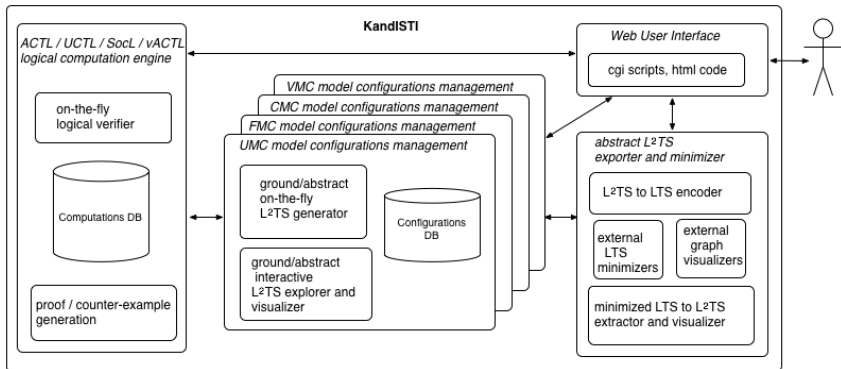


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Overall structure of the model checkers

Statespace generation (depending on the underlying computational model) is **separated** from L^2TS analysis

Explicit abstraction mechanism allows to specify which details of the model become observable labels on the L^2TS ' states and transitions



VMC: Variability Model Checker

Efficient **bounded**, **on-the-fly** model checking, providing **explanations**

Profits from optimizations of KandISTI

VMC now accepts as input a specification in a value-passing modal process algebra, possibly with additional n -ary variability constraints

- interactively explore the model (MTS)
- derive and explore (all) the model's valid variants (LTSs)
- visualize the model/variants graphically as MTS/LTSs
- verify v-ACTL properties over MTSs/LTSs
- interactively explain why a property is (not) satisfied

VMC (v6.0, released in June 2014) is freely usable online:

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Main ingredient: Modal Transition Systems (MTS)

- LTS distinguishing admissible **may** and necessary **must** transitions
Larsen, Thomsen @ LICS'88 (each necessary transition is also admissible)
- Recognized as a useful model to describe in a compact way the possible **behavior** of all the products (LTS) of a product family
Fischbein, Uchitel, Braberman @ ROSATEA'06; Fantechi, Gnesi @ ESEC/FSE'07, SPLC'08;
Larsen, Nyman, Wąsowski @ ESOP'07; Lauenroth, Pohl, Töhning @ ASE'09
- MTS cannot model variability constraints regarding **alternative** features, nor regarding **requires/excludes** inter-feature relations
Asirelli, ter Beek, Fantechi, Gnesi @ iFM'10
- Our solution: add a set of **variability constraints** to the MTS to be able to decide which derivable products (LTS) are valid ones
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Refinement (classic)

- Implementations of an MTS are LTSs: refine a partial description (with dotted edges) into a more detailed one (only solid edges), reflecting increased knowledge on **admissible but not necessary** behavior
- Does fit SPLE notion that each product of a product family is a refinement of that family, based on the understanding that an LTS (product behavior) conforms to the MTS (family behavior)



- But may result in a possibly **infinite** set of, potentially not bisimilar, implementations (explosion due to the unbounded expansion of loops)

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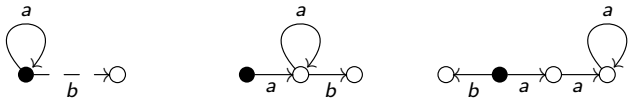
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- VMC: a simpler notion of refinement preserves the exact **original branching structure** of the MTS in the products, corresponding to the modelers' intuition ("a feature either is present or is not")
- Implementations: "turn a dotted edge into a solid edge or remove it altogether"



- Immediate advantage: **limited** set of product behaviors

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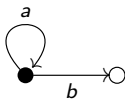
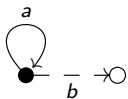
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Assumptions (implemented in VMC)

- An action models a piece of functionality (a feature if you like)
- **Coherence:** no solid edge is labeled with the same action as a (different) dotted edge (“a feature either is optional or is not”)
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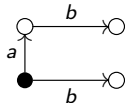
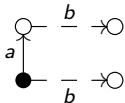
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Variability constraints (implemented in VMC)

Variability constraints of the form **AL**Ternative, **EX**cludes, **REQ**uires, but also compositions like a REQ (b ALT c)



a ALT b



Semantics in ACTL:

a_1 ALT a_2 ALT \dots ALT a_n :

$$\bigvee_{1 \leq i \leq n} ((EF \{a_i\} \text{ true}) \wedge \bigwedge_{1 \leq j \neq i \leq n} (\neg EF \{a_j\} \text{ true}))$$

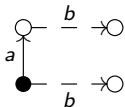
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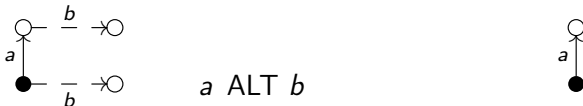
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Product derivation (implemented in VMC)

A **product LTS** is obtained from a **coherent** family MTS as follows:

1. include **all** (reachable) must transitions (solid edges)
2. include **subset** of the (reachable) may but not must transitions (dotted edges), remove others
3. satisfy **consistency** assumption
4. satisfy all **variability constraints**

Each selection gives rise to a different variant

Modeling MTS/LTS as L^2TS makes VMC a product of the KandISTI family of model checkers

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A value-passing modal process algebra (input to VMC)

Let \mathcal{A} be a set of actions, let $a \in \mathcal{A}$ and let $L \subseteq \mathcal{A}$

Processes are built from terms and actions according to the syntax

$$N ::= [P]$$

$$P ::= K(e) \mid P/L/P$$

$[P]$ denotes a closed system, i.e. it cannot evolve on input actions $a(?v)$

$K(e)$ is process identifier from set of process definitions of form $K(v) \stackrel{\text{def}}{=} T$

$$T ::= nil \mid K(e) \mid A.T \mid T + T \mid [e \bowtie e] T$$

$$A ::= a(e) \mid a(\text{may}, e) \mid a(?v) \mid a(\text{may}, ?v)$$

$$e ::= v \mid \text{int} \mid e \pm e$$

$\bowtie \in \{<, \leq, =, \neq, \geq, >\}$, v is a variable, int is an integer, $\pm \in \{+, -, \times, \div\}$

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- nil terminated process that has finished execution
- K process identifier that is used for modelling recursive sequential processes
- $A.P$ process that can execute action A and then behave as P
- $P + Q$ process that can non-deterministically choose to behave as P or as Q
- $P / L / Q$ process formed by the parallel composition of P and Q (may synchronize on actions in L and interleave others)

Distinguish **must** actions a and **may but not must** actions a (*may*)
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Semantics in SOS style over MTS

$$\text{(sys)} \frac{P \xrightarrow{a(e)} P'}{[P] \xrightarrow{a(e)} [P']}$$

$$\text{(act}_{\square}\text{)} \frac{}{\alpha.P \xrightarrow{\alpha} P} \quad \alpha \in \{a(e), a(?v)\}$$

$$\text{(or}_{\square}\text{)} \frac{P \xrightarrow{\alpha} P'}{P + Q \xrightarrow{\alpha} P'} \quad \alpha \in \{a(e), a(?v)\}$$

$$\text{(int}_{\square}\text{)} \frac{P \xrightarrow{\ell} P'}{P / L / Q \xrightarrow{\ell} P' / L / Q} \quad \ell \notin L$$

$$\text{(par}_{\square}\text{)} \frac{P \xrightarrow{a(e_1)} P' \quad Q \xrightarrow{a(e_2)} Q'}{P / L / Q \xrightarrow{a} P' / L / Q'} \quad a \in L, e_1 = e_2$$

$$\text{(par}_{\square}\text{)} \frac{P \xrightarrow{a(?v)} P' \quad Q \xrightarrow{a(e)} Q'}{P / L / Q \xrightarrow{a} P'[e/v] / L / Q'} \quad a \in L$$

$$\text{(guard)} \frac{}{[e_1 \bowtie e_2] P(e_3) \rightarrow P(e_3)} \quad e_1 \bowtie e_2$$

Similarly in case of may actions and for the remaining operators

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$$\text{(or}_{\square}\text{)} \frac{P \xrightarrow{\alpha} P'}{P + Q \xrightarrow{\alpha} P'} \quad \alpha \in \{a(e), a(?v)\}$$

$$\text{(int}_{\square}\text{)} \frac{P \xrightarrow{\ell} P'}{P / L / Q \xrightarrow{\ell} P' / L / Q} \quad \ell \notin L$$

$$\text{(par}_{\square}\text{)} \frac{P \xrightarrow{a(e_1)} P' \quad Q \xrightarrow{a(e_2)} Q'}{P / L / Q \xrightarrow{a} P' / L / Q'} \quad a \in L, e_1 = e_2$$

$$\text{(par}_{\square}\text{)} \frac{P \xrightarrow{a(?v)} P' \quad Q \xrightarrow{a(e)} Q'}{P / L / Q \xrightarrow{a} P'[e/v] / L / Q'} \quad a \in L$$

$$\text{(guard)} \frac{}{[e_1 \bowtie e_2] P(e_3) \rightarrow P(e_3)} \quad e_1 \bowtie e_2$$

Similarly in case of may actions and for the remaining operators

ACTL: action-based CTL

Syntax over **action formulas** (boolean compositions of actions, denoted by ψ), **state formulas** (ϕ) and **path formulas** (π)

$$\begin{aligned}\phi &::= \text{true} \mid \neg\phi \mid \phi \wedge \phi \mid [\psi]\phi \mid \langle\psi\rangle\phi \mid E\pi \mid A\pi \mid \\ &\quad \mu Y.\phi(Y) \mid \nu Y.\phi(Y) \\ \pi &::= X\{\psi\}\phi \mid [\phi\{\psi\}U\{\psi'\}\phi'] \mid [\phi\{\psi\}W\{\psi'\}\phi'] \mid \\ &\quad [\phi\{\psi\}U\phi'] \mid [\phi\{\psi\}W\phi'] \mid F\phi \mid F\{\psi\}\phi \mid G\phi\end{aligned}$$

(Y is a propositional variable, $\phi(Y)$ is syntactically monotone in Y)

μ and ν : **recursion** (“finite looping”/“liveness” and “looping”/“safety”)

X, U, W, F : **action-based** neXt, Until, Weak until, Future (“eventually”)

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v-ACTL: variability-aware ACTL (implemented in VMC)

v-ACTL[□]:

$$\phi ::= \text{false} \mid \text{true} \mid \phi \wedge \phi \mid \phi \vee \phi \mid [\psi]\phi \mid \langle \psi \rangle^{\square} \phi \mid \\ EF^{\square} \phi \mid EF^{\square} \{\psi\} \phi \mid AF^{\square} \phi \mid AF^{\square} \{\psi\} \phi \mid AG \phi$$

any formula that is **true** for MTS, is also **true** for all products (LTSs)

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Informal semantics of v-ACTL

$[\psi] \phi$ in all next states reachable by a **may** transition executing an action satisfying ψ , ϕ holds

$[\psi]^{\square} \phi$ in all next states reachable by a **must** transition executing an action satisfying ψ , ϕ holds

$\langle \psi \rangle \phi \equiv \neg [\psi] \neg \phi$ a next state exists, reachable by a **may** transition executing an action satisfying ψ , in which ϕ holds

$\langle \psi \rangle^{\square} \phi \equiv \neg [\psi]^{\square} \neg \phi$ a next state exists, reachable by a **must** transition executing an action satisfying ψ , in which ϕ holds

$\langle \psi \rangle^{\square}$ and $[\psi]^{\square}$ represent the classic **deontic** modalities O and P

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Informal semantics of v-ACTL (cont'd)

$E \pi$ there exists a full path on which π holds

$A \pi$ on all possible full paths, π holds

$F \phi$ there exists a future state in which ϕ holds

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$G \phi \equiv \neg F \neg \phi$ the path is a full path on which ϕ holds in all states

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In **Quanticol** we collaborate with *PisaMo* (responsible for the public BSS *CicloPi* in Pisa, currently only some 150 bikes and 15 stations)

We recall the small case study presented by Stefania in her keynote

Inspired by Fricker, Gast @ arXiv, September 2013

We model 2 user groups that can take a bike from docking station I , ride it for a while (not modeled), and deliver it to docking station J

Initially, docking station I has 1 bike, which it gives (when available) to a requesting user or accepts from a returning user

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Value-passing BSS specification

```
Station(I,N,J,M) = request(I).
  ( [N=0] nobike(I).Station(I,N,J,M) +
    [N>0] bike(I).Station(I,N-1,J,M) ) +
return(I).Station(I,N+1,J,M) +
redistribute(may,?FROM,?TO,?K).
  ( [TO = I] Station(I,N+K,J,M) +
    [TO /= I] Station(I,N,J,M) ) +
[N > M] redistribute(may,I,J,N-M).Station(I,M,J,M)
```

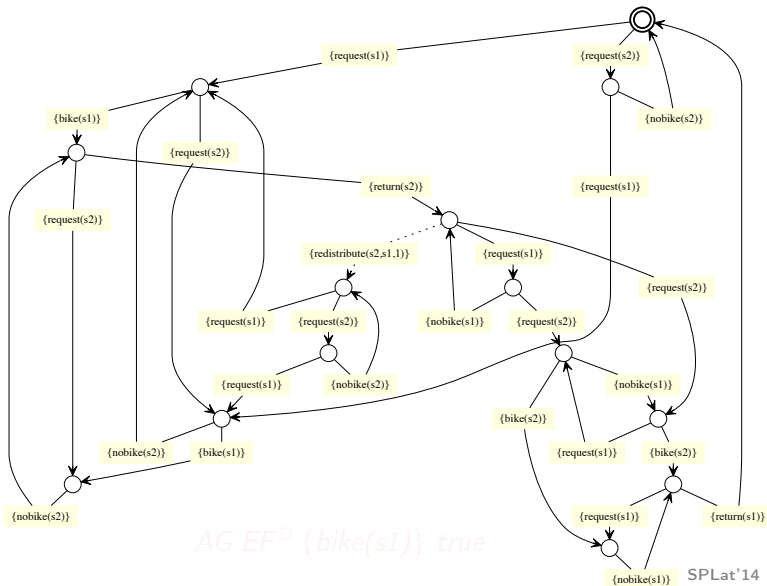
```
net STATIONS = Station(s1,1,s2,1) /redistribute/ Station(s2,0,s1,0)
```

```
Users(I,J) = request(I).
  ( bike(I).return(J).Users(I,J) +
    nobike(I).Users(I,J) )
```

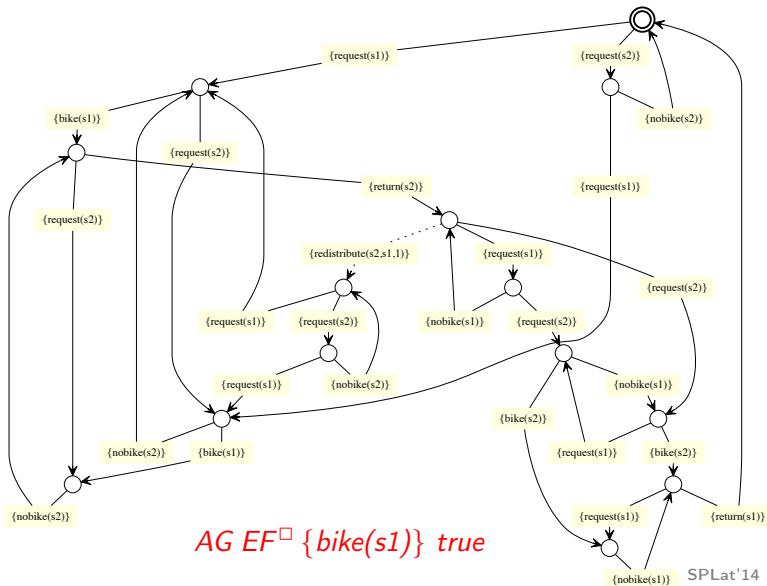
```
net USERS = Users(s1,s2) // Users(s2,s1)
```

```
net BSS = STATIONS /request,bike,nobike,return/ USERS
```

MTS with parameters and values



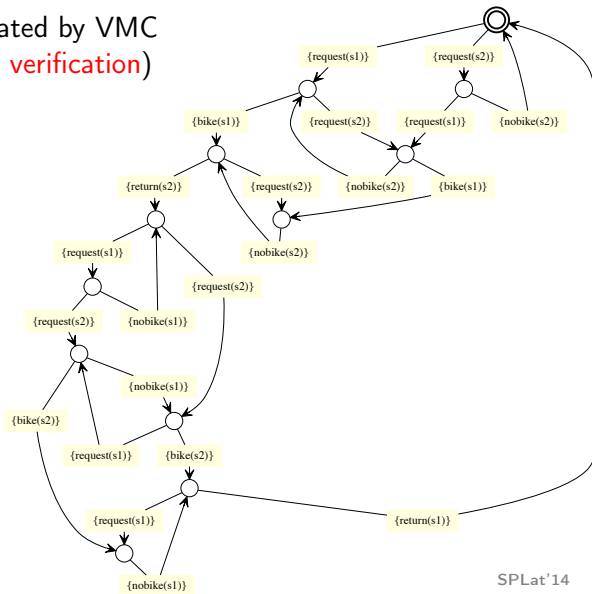
MTS with parameters and values



$AG EF^{\square} \{bike(s1)\} true$

v-ACTL[□] formula: true \forall products

Products generated by VMC
(not needed for verification)



SPL Analysis Strategies

Thüm, Apel, Kätstner, Schaefer, Saake @ ACM Comput. Surv., 2014

Product-based analyses: verification on individually derived products, or at most a subset

Family-based analyses: verification on entire product family **at once**, using available variability knowledge about valid feature configurations to deduce the results for all its products

Possible trade-off (e.g. time vs. memory complexity)?

- Brute-force product-based analysis with model checkers highly optimized for single system engineering (e.g. SPIN, mCRL2)

spinroot.com www.mcr12.org (next talk!)

- Highly innovative family-based analysis with model checkers developed specifically for SPL (e.g. SNIP, NuSMV extension)

Classen et al. @ STTT, 2012; Classen et al. @ IEEE TSE, 2013; Classen et al. @ Sci. Comput. Program., 2014

⇒ Implement some SPL-specific features in VMC?

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Challenges ahead

Study and implement the **derivation** of products in the presence of both **structural** constraints (ALT, EXC, REQ from feature models) and **quantitative** constraints (so-called attributed feature models)?

Weighted MTS?

Parameter values in constraints?

Explicit **behavioral variability constraints** like $X \{a\} \text{ ALT } X \{b\}$?
(consistency assumption!)

Study the **inheritance** of the result of verifying a v-ACTL formula over an MTS by its product LTS in the presence of such types of constraints

Scalability?

Comparison with other tools (e.g. ProVeLines)

Publicity: start preparing for FMSPLE'15 in London, UK

Formal Methods and Analysis in Software Product Line Engineering
(FMSPLE'15)

6th International Workshop

London, UK, April 11, 2015

(co-located with ETAPS'15)

⇒ <http://fmsple15.isti.cnr.it/> ⇐

Submission deadline: January 30, 2015

PC chairs:

- Joanne Atlee (University of Waterloo, Canada)
- Stefania Gnesi (ISTI-CNR, Pisa, Italy)